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**AMENDMENT TO SPECIFICATION**

**IN THE SPECIFICATION:**

A marked-up copy of the changes to selected paragraph(s) is provided below. Please enter these changes to the specification in the record.

Please change paragraph spanning pages 6 and 7 as follows.

Still referring to Figure 2, the depalletizer subsystem 120 includes a stand 121, a lift device 122 and a pallet lift conveyor 123, provided on the lift device 122. It should be readily recognized by those of ordinary skill in the art that the lift device 122 may be any known lift mechanism such as a scissors-type lift mechanism, pneumatic or hydraulic cylinder/piston assembly, a linear actuator, a chain or belt driven mechanism or the like. The pallet lift conveyor 123 is capable of rotating, as designated by arrow "A". By way of one example, in a lowered position, the pallet lift conveyor 123 may rotate 90 degrees, if necessary, so that short ends of the bundles on the top layer of bundles on the pallet (placed on the pallet input station 110) will face the staging conveyor 200. This rotation may be effected by a gear system, a belt and gear system or other known mechanisms "R". Additionally, in one embodiment, the lift device 122 may provide a range of motion between the pallet input, e.g., lowered position, to approximately one bundle height above the staging conveyor 200. In this lowered position, rollers or other conveyance 112 of the pallet input station 110 and/or the pallet lift conveyor 123 will become activated, via the controller "C" to transport the pallet onto the pallet lift conveyor 123. The

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conveyor system of the depalletizer subsystem 120 is represented generally as reference numeral 123a. The controller may receive a signal from any known sensor "S", for example, a motion sensor, a photo sensor or the like, or may be activated by a position of the depalletizer, itself, when in the lowered position.